



Short-Term Forecasting of GDP at the Bank of Latvia

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Short-term Forecasting of GDP at the Bank of Latvia

- Set of models:
 - Traditional bridge equations;
 - Bridge equations in state-space form;
 - Dynamic factor models.

Operative indicators

- GDP data are available at quarterly frequency and become available with a lag:
 - Flash estimate ~ 2 months;
 - Official release ~ 3 months.
- Instead, most data relating GDP are available faster and at monthly frequency:
 - Money aggregate M3;
 - Industrial production;
 - Retail turnover, etc.

Dataset

- Real-time GDP database by monthly breakdown (monthly revisions) of expenditure and production side.
- Monthly indicators on economic activity including:
 - industrial production;
 - retail turnover;
 - exports, imports;
 - inflation;
 - money aggregates;
 - unemployment, vacancies;
 - taxes, etc.
- Business and consumer surveys.

Aggregated vs. disaggregated approach

- Three approaches:
 - GDP at aggregated level using monthly indicators;
 - GDP by expenditure side:
$$Y_{(\text{expenditure})} = C + G + I + X + M;$$
 - GDP by output side:
$$Y_{(\text{output})} = AB + CDE + F + G + I + HJKO + LMN + TS;$$
- Each component of expenditure and output basis has its own set of monthly indicators with appropriate economic meaning.



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GDP forecasting using traditional bridge equations

Concept of bridge equations

- Bridge equations describe the correlation between quarterly variables such as GDP (or its components) and monthly indicators.
- Monthly indicators are converted to quarter frequency in line with their characteristics as stock or flow variables.
- Then dependent variable is regressed on monthly indicators in quarterly frequency.

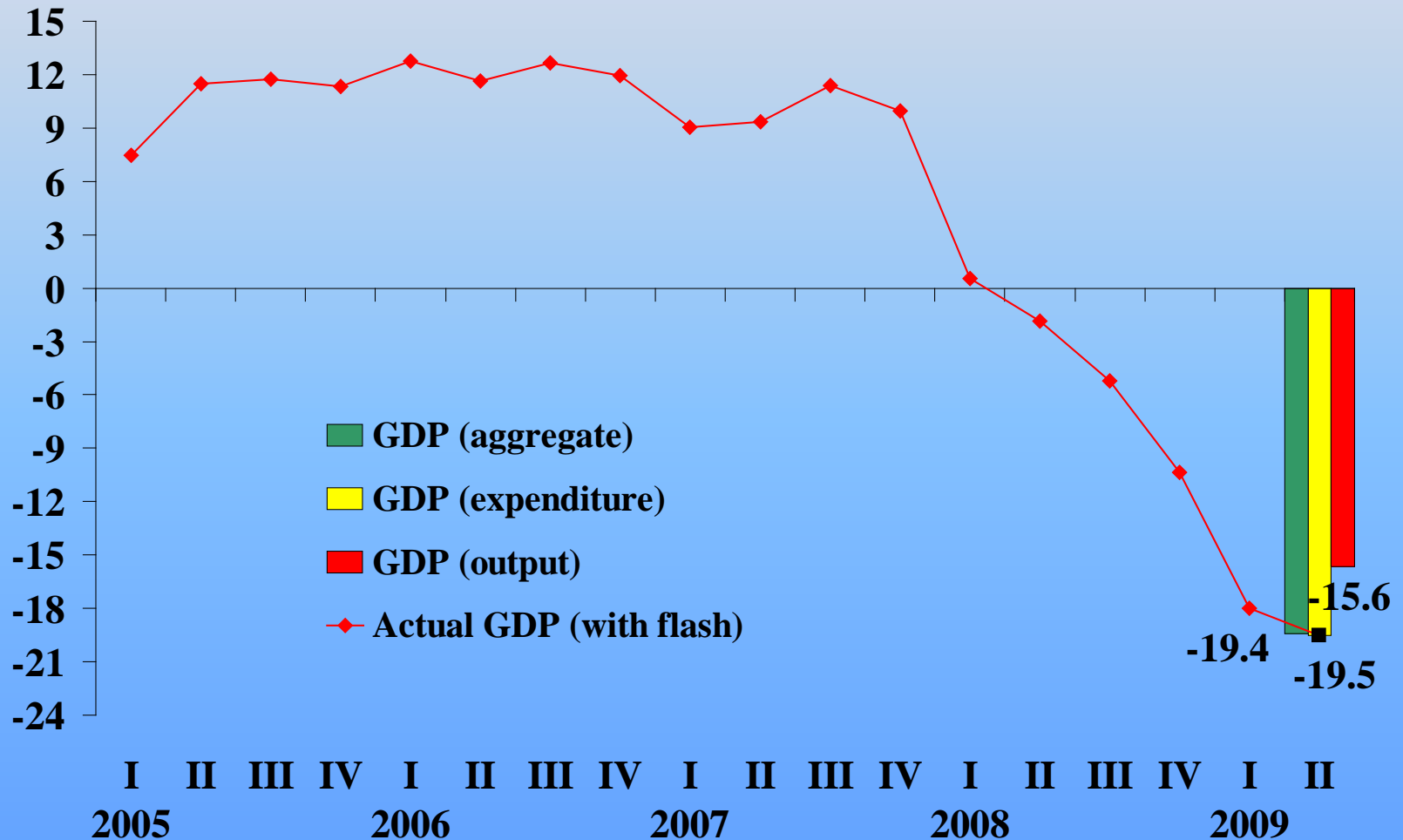
Concept of bridge equations

Quarterly GDP growth Lagged value of GDP growth Monthly indicators

$$y_{t_q} = \rho(L) y_{t_q} + \sum_{j=1}^k \delta_j(L) x_{j,t_q}^{mq} + \varepsilon_{t_q}$$

- y_{t_q} – GDP quarterly growth;
- x^{mq} – set of monthly indicators converted to quarterly frequency;
- k – number of indicators.

Bridge equations' forecasts



GDP interpolation and short-term
forecasting using bridge
equations in state-space form

State-space form

- The use of bridge equations in state-space form helps to find correlations between quarterly GDP data and monthly indicators on a monthly basis.
- Two equations:
 - Transition equation: unobservable monthly GDP growth depends on operative monthly indicators;
 - Measurement equation: sum of 3 months should be equal to the GDP quarter value.
- Solved by Kalman filter.

State-space form

Lagged GDP growth

Monthly GDP growth

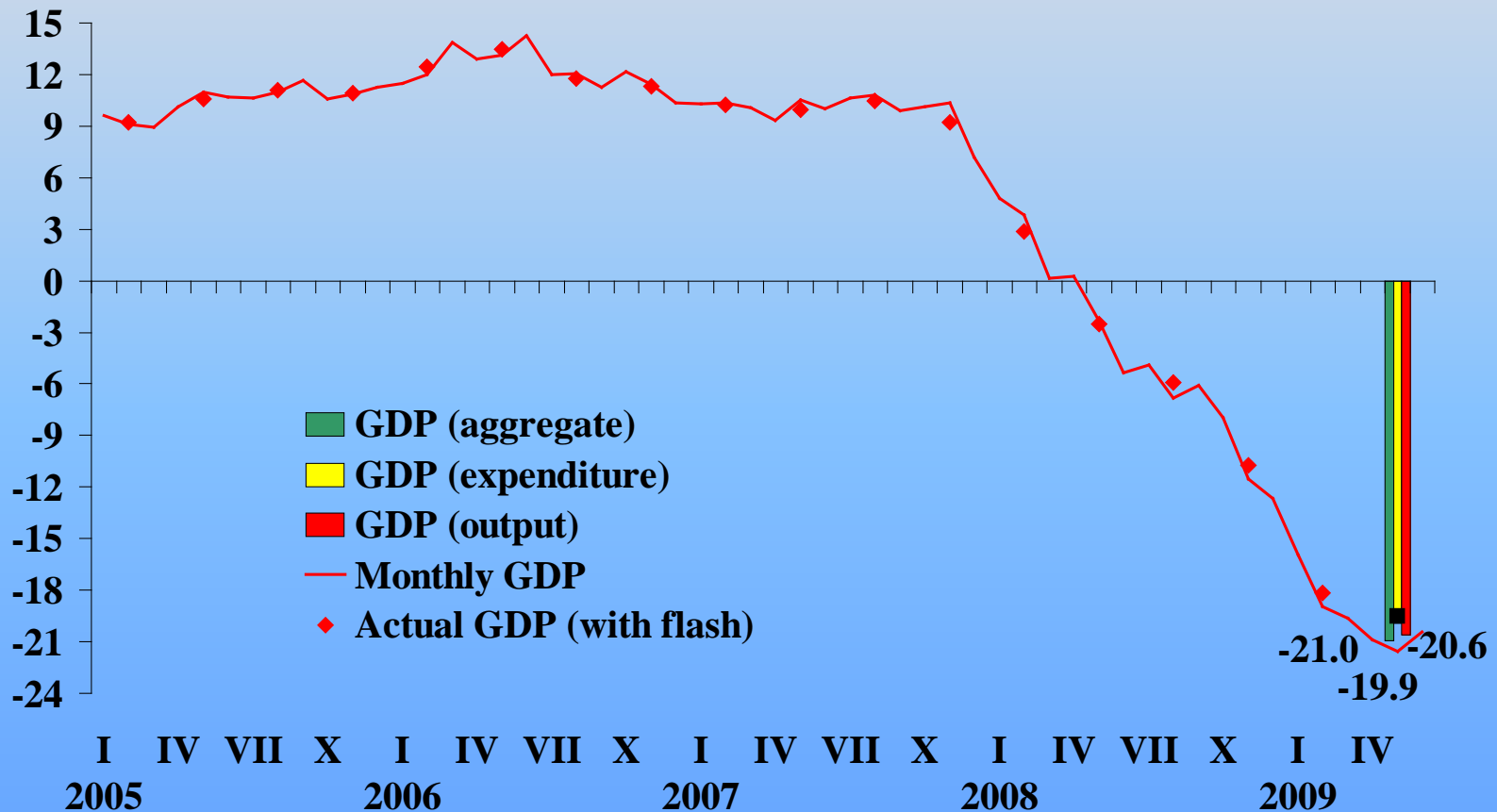
Operative monthly indicators

$$\begin{pmatrix} \Delta \ln y_{t+1}^m \\ \Delta \ln y_t^m \\ \Delta \ln y_{t-1}^m \\ \Delta \ln y_{t-2}^m \\ \Delta \ln y_{t-3}^m \\ e_{t+1} \end{pmatrix} = \begin{pmatrix} \zeta & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \Delta \ln y_t^m \\ \Delta \ln y_{t-1}^m \\ \Delta \ln y_{t-2}^m \\ \Delta \ln y_{t-3}^m \\ \Delta \ln y_{t-4}^m \\ e_t \end{pmatrix} + \begin{pmatrix} \beta_1 & \cdots & \beta_N \\ 0 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 0 \end{pmatrix} \begin{pmatrix} \Delta \ln x_{1,t}^m \\ \vdots \\ \Delta \ln x_{N,t}^m \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \sigma^2 \end{pmatrix} u_{t+1}$$

$$\Delta \ln y_{\tau}^Q = \frac{1}{3} \Delta \ln y_t^m + \frac{2}{3} \Delta \ln y_{t-1}^m + \Delta \ln y_{t-2}^m + \frac{2}{3} \Delta \ln y_{t-3}^m + \frac{1}{3} \Delta \ln y_{t-4}^m + \xi_{\tau}$$

Quarterly GDP growth is linked to the monthly GDP growth rates

GDP growth forecast using monthly GDP estimates



State-space form advantages and disadvantages

- Advantages:
 - Helps to estimate monthly GDP.
- Disadvantages:
 - Using short time series Kalman filter results are unstable;
 - Results are sensitive to set of variables one use in state-space form.

GDP forecasting using dynamic factor models

Dynamic factor models

- Regression analysis usually uses 4-5 variables at most:
 - Technical difficulties (number of variables cannot exceed number of observations);
 - Models become unstable or inefficient.
- However, there are a lot of variables which contain important information about economic activity.
- Factor models allow to use all that information without losing too much degrees of freedom.

Concept of Factor Models

- There exist few unobservable factors, which explain most of economic indicators' fluctuations.
- Those factors are independent from each other.
- We reduce all necessary information about economic activity into unobservable factors.
- We are able to calculate unobservable components using Principal Components Analysis.

Incomplete datasets

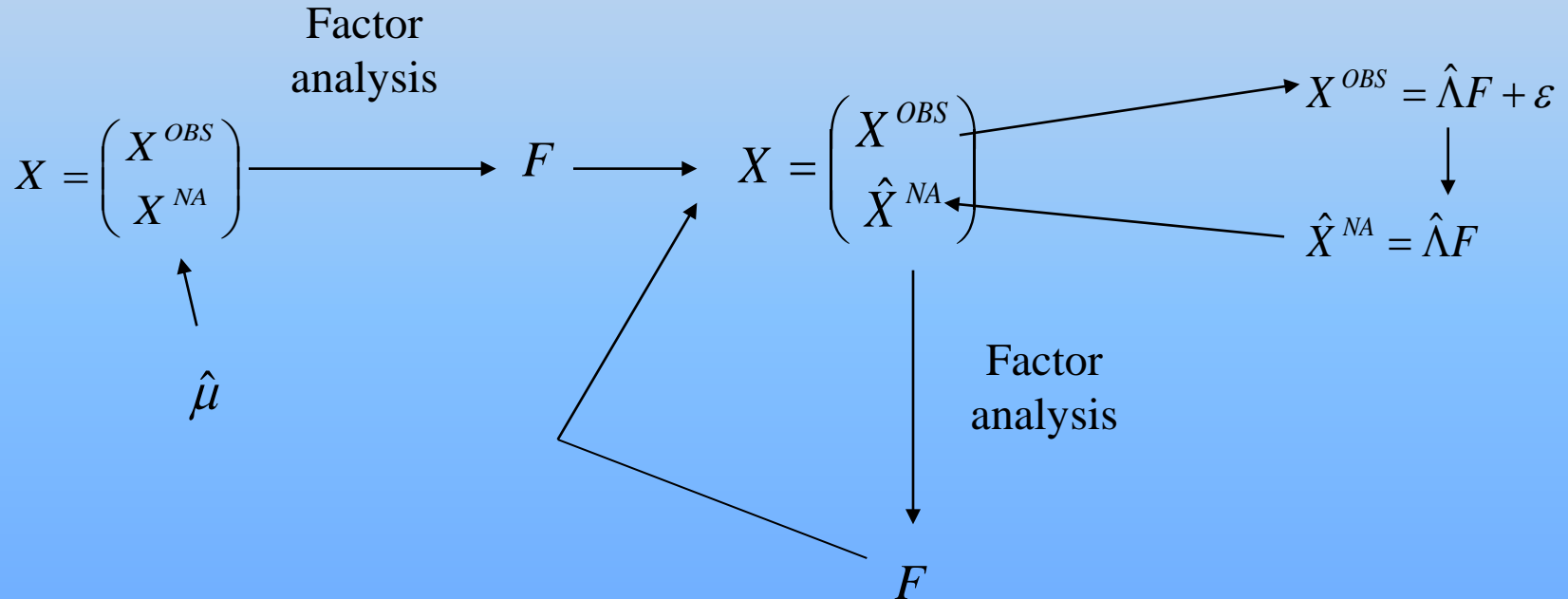
| | X1 | X2 | X3 | X4 | X5 | X6 | X7 | X8 | X9 | X10 | X11 | X12 |
|---------|-------|-------|-------|-------|-------|-------|-------|---------|---------|---------|-------|-------|
| 1999M07 | -21.2 | -9.9 | N/A | N/A | -43.5 | 91.2 | -30.1 | N/A | N/A | N/A | 111.0 | 172.0 |
| 1999M08 | -21.1 | -9.7 | N/A | N/A | -44.0 | 91.3 | -23.9 | N/A | N/A | N/A | 110.5 | 175.3 |
| 1999M09 | -20.9 | -9.6 | N/A | N/A | -45.5 | 91.5 | -22.5 | N/A | N/A | N/A | 112.0 | 180.0 |
| 1999M10 | -11.8 | -10.2 | N/A | N/A | -44.5 | 96.0 | -22.3 | N/A | N/A | N/A | 111.1 | 181.4 |
| 1999M11 | -11.4 | -10.2 | N/A | N/A | -45.5 | 96.3 | -18.3 | N/A | N/A | N/A | 113.3 | 183.3 |
| 1999M12 | -11.1 | -10.1 | N/A | N/A | -46.0 | 96.5 | -15.6 | N/A | N/A | N/A | 115.2 | 184.6 |
| 2000M01 | -14.3 | -2.7 | N/A | N/A | -32.0 | 91.1 | -16.7 | 1758 | -13595 | 11068 | 114.4 | 186.4 |
| 2000M02 | -14.0 | -2.3 | N/A | N/A | -32.5 | 90.9 | -15.8 | -47391 | 31978 | 14901 | 115.4 | 185.8 |
| 2000M03 | -13.7 | -2.4 | N/A | N/A | -32.5 | 90.7 | -17.3 | -10534 | 11097 | -24232 | 117.0 | 185.2 |
| : | : | : | : | : | : | : | : | : | : | : | : | : |
| 2001M04 | -3.4 | 14.9 | N/A | N/A | 1.0 | 99.5 | -2.4 | -36353 | 16562 | -8532 | 120.9 | 178.4 |
| 2001M05 | -6.6 | 19.4 | N/A | N/A | 1.0 | 102.9 | -3.0 | 473 | -28502 | 8225 | 122.0 | 178.5 |
| 2001M06 | -3.3 | 28.6 | N/A | N/A | 1.5 | 104.3 | -10.1 | -102918 | 137589 | -13223 | 124.3 | 178.1 |
| 2001M07 | 1.7 | 13.8 | N/A | N/A | N/A | 103.7 | -10.5 | -47712 | 102368 | -26735 | 123.6 | 179.2 |
| 2001M08 | 2.5 | 9.5 | N/A | N/A | N/A | 106.3 | -6.2 | 51661 | -58787 | 13167 | 121.1 | 181.2 |
| 2001M09 | 0.4 | 9.1 | N/A | N/A | N/A | 103.8 | -9.6 | 5170 | 27891 | 4536 | 121.3 | 182.3 |
| 2001M10 | -1.2 | 12.7 | N/A | N/A | N/A | 100.7 | -7.0 | -2212 | 46315 | -22871 | 121.2 | 181.3 |
| 2001M11 | -2.0 | 10.2 | N/A | N/A | N/A | 100.3 | -7.6 | 143211 | 1625 | -111120 | 122.0 | 180.9 |
| 2001M12 | -5.5 | 4.3 | N/A | N/A | N/A | 98.8 | -6.4 | 89525 | 109352 | -28649 | 121.1 | 180.2 |
| 2002M01 | 3.9 | 7.4 | N/A | N/A | N/A | 104.2 | -7.3 | 5434 | 10808 | 384 | 120.6 | 180.0 |
| 2002M02 | 3.9 | -0.1 | 10.3 | N/A | N/A | 107.3 | -7.0 | -9898 | -11061 | 13202 | 121.6 | 180.4 |
| 2002M03 | 6.2 | 4.5 | 6.9 | N/A | N/A | 110.8 | -7.7 | -22522 | 43591 | -5050 | 121.1 | 180.7 |
| 2002M04 | -1.9 | 9.1 | 8.9 | N/A | N/A | 109.5 | -8.2 | -53069 | 55865 | 11920 | 120.6 | 180.2 |
| 2002M05 | -1.6 | 18.8 | 9.0 | 2.1 | 17.6 | 107.1 | -8.9 | -39135 | 64181 | 9461 | 119.3 | 179.7 |
| 2002M06 | -1.5 | 21.2 | 9.1 | 9.8 | 17.3 | 107.5 | -13.6 | 25102 | -73701 | 10965 | 116.9 | 179.1 |
| : | : | : | : | : | : | : | : | : | : | : | : | : |
| 2009M05 | -29.0 | -44.2 | -40.9 | -41.5 | -69.5 | 70.3 | -31.2 | 14893 | -276095 | 16535 | 105.8 | 171.1 |
| 2009M06 | -27.7 | -42.0 | -40.5 | -45.6 | -70.7 | 70.2 | -29.0 | 11527 | -308734 | 99374 | 105.9 | 171.5 |
| 2009M07 | -26.7 | -34.0 | -39.7 | -38.4 | -70.3 | 71.5 | -28.7 | N/A | N/A | N/A | N/A | N/A |

Expectation-maximization algorithm

- Database X could be divided into two subsets:
 - X^{NA} – missing observations;
 - X^{OBS} – available observations.
- We can estimate missing observations using expectation-maximization (EM) algorithm.

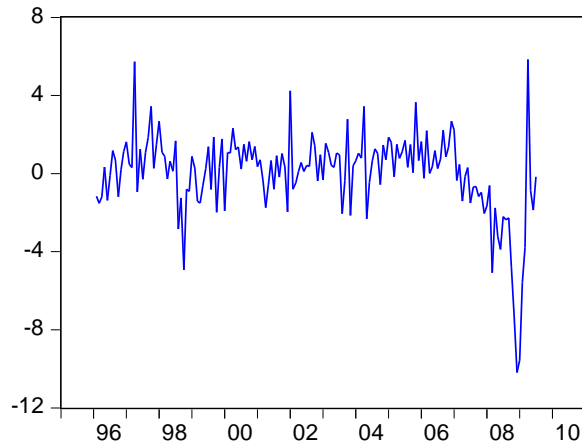
Expectation-maximization algorithm

- Stop, when changes in F are small:

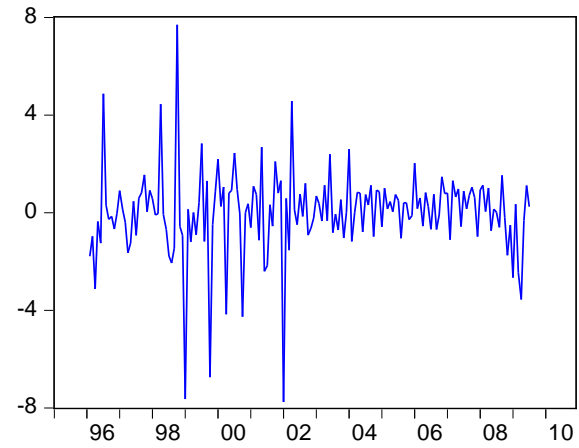


Unobservable factors

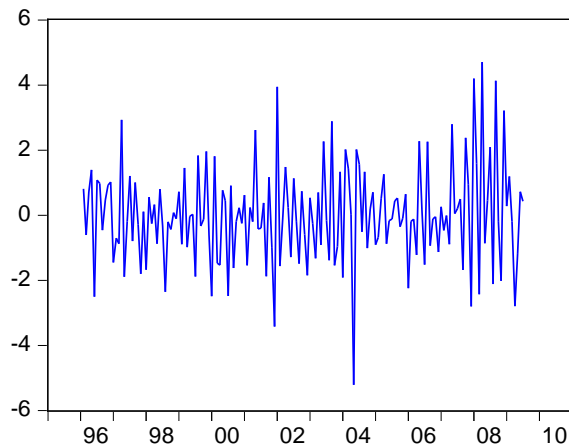
1.factor



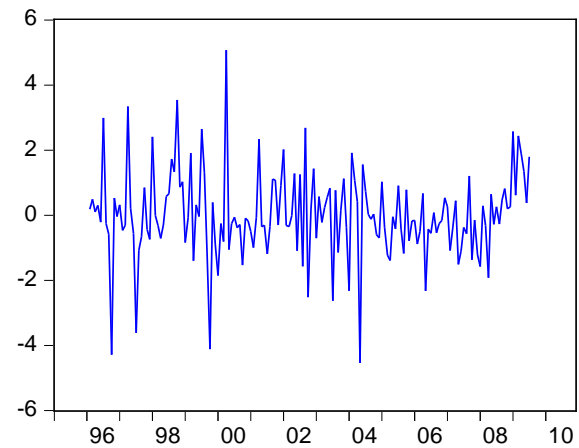
2.factor



3.factor



4.factor



Forecasting using dynamic factor models

- While modelling and forecasting with factor models, one should consider the following:
 - Number of unobservable factors;
 - Number of lags of latent factors;
 - Number of lags of endogenous variable.
- We chose parameters, which maximize the forecasting ability of the model (RMSFE).

Forecasting using dynamic factor models

- 1-step ahead:

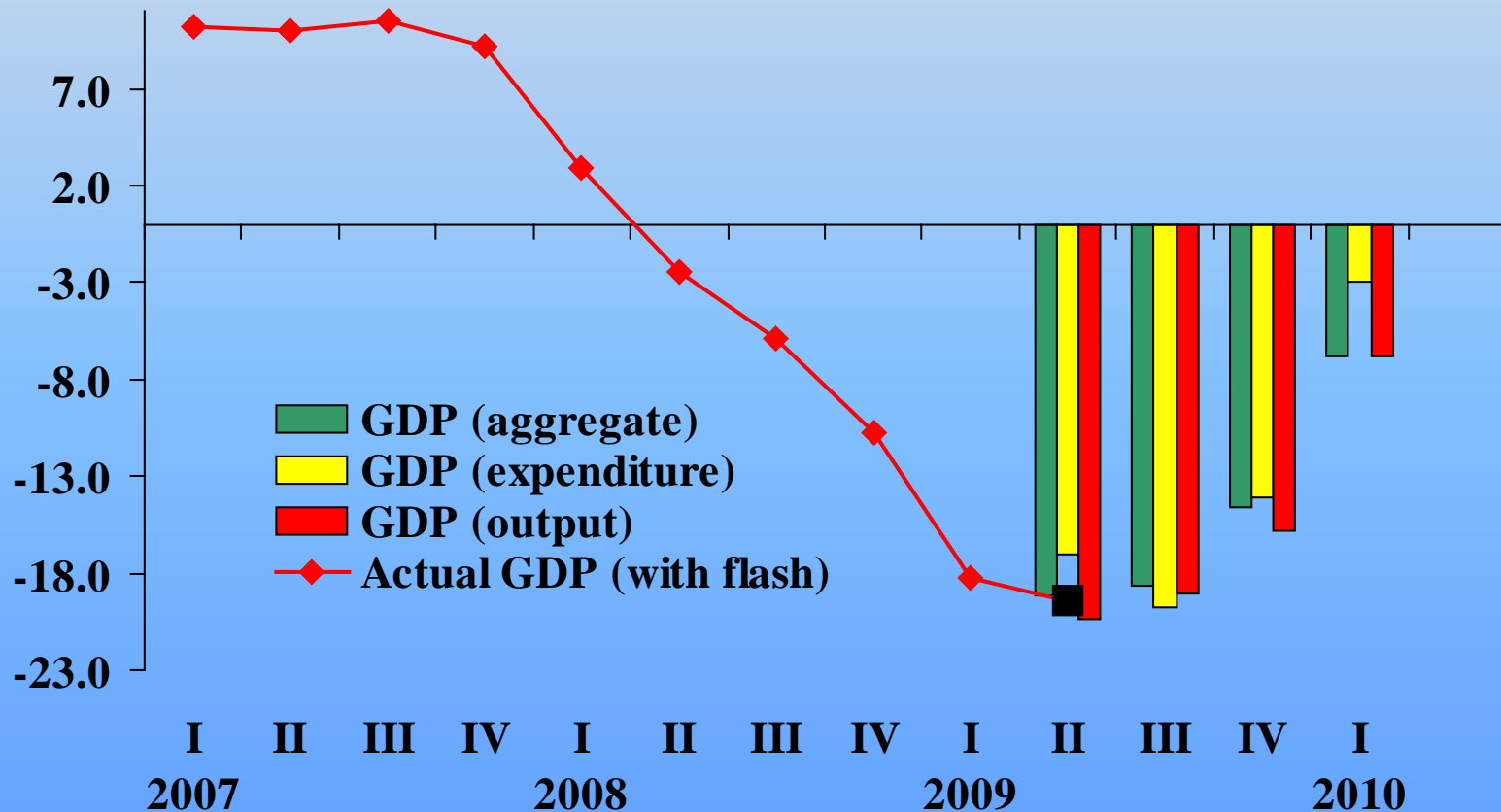
$$\hat{y}_{t+1}^1 = \alpha_1 + \beta_1(L)F_t + \gamma_1(L)y_t$$

- h-steps ahead:

$$\hat{y}_{t+h}^h = \alpha_h + \beta_h(L)F_t + \gamma_h(L)y_t$$

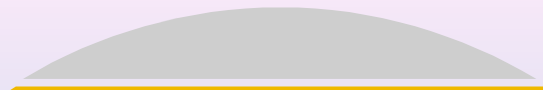
Dynamic factor models forecasts

- Next 4 quarters forecasts (model: 1 factor, 1 factor lag, none GDP lags)



Factor models advantages and disadvantages

- Advantages:
 - Factor models allow to use large datasets;
 - Using the same dataset one could forecast necessary macroeconomic variable, not even GDP.
- Disadvantages:
 - There is little economic interpretation for latent factors and equations;
 - Factor model tracks only past observations therefore predictability of the model is limited when structural breaks occur;
 - It is difficult to determine number of variables in dataset. Even more, the greater number of variables does not necessary improve model's predictability.



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Comparison of models' forecasting ability

Comparing models' forecasting ability

- There are 9 models for short-term forecast – which one to use?
- Start to look at out-of-sample forecast
 - 2/3 of sample - actual values, 1/3 - out of sample forecast.
- RMSFE indicates the forecasting performance of the model in the past:

$$RMSFE = \sqrt{\frac{1}{T} \sum_{i=1}^T \underbrace{(y_i - \hat{y}_i^F)^2}_{\text{Forecasting error}}}$$

Forecasting error

Forecasting ability: aggregated approach

**GDP root mean squared forecasting error (RMSFE) (pp.)
2004Q4-2009Q1**

| Horizon | Traditional bridge | Bridge in state-space | Factor | Combination |
|---------|--------------------|-----------------------|--------|-------------|
| +Q1 | 2.61 | 2.58 | 2.56 | 2.52 |
| +Q2 | | | 3.45 | 3.92 |
| +Q3 | | | 6.34 | 6.72 |
| +Q4 | | | 8.13 | 8.63 |

* Forecast combination is just a simple average of individual models

Forecasting ability: disaggregated by expenditure

**1 quarter ahead GDP RMSFE (pp.) on expenditure basis,
2004Q4-2009Q1**

| Model | Y(expenditure) | Private consumption | Government consumption | Investment | Exports | Imports |
|-----------------------|----------------|---------------------|------------------------|------------|---------|---------|
| Traditional Bridge | 4.34 | 5.11 | 9.7 | 14.55 | 4.12 | 4.74 |
| Bridge in state-space | 4.1 | 5.59 | 10.93 | 15.13 | 3.88 | 4.74 |
| Factor | 2.12 | 5.32 | 9.6 | 12.86 | 3.69 | 7.02 |

Forecasting ability: disaggregated by output

**1 quarter ahead GDP RMSFE (pp.) on output basis,
2004Q4-2009Q1**

| Model | Y(output) | AB | CDE | F | G | I | HJKO | LMN | TS |
|-----------------------|-----------|------|------|------|------|------|------|------|-------|
| Traditional bridge | 2.77 | 5.25 | 2.86 | 4.94 | 3.53 | 7.34 | 3.39 | 2.8 | 14.52 |
| Bridge in state-space | 2.52 | 4.46 | 2.99 | 5.9 | 3.51 | 8.26 | 3.28 | 5.01 | 15.56 |
| Factor | 2.58 | 5.64 | 2.26 | 5.65 | 3.29 | 9.22 | 3.15 | 3.96 | 16.53 |

Practical use

- Results of the short-term forecasting models are reported to the Board of the Bank of Latvia and Monetary Policy Department colleagues on a weekly basis.